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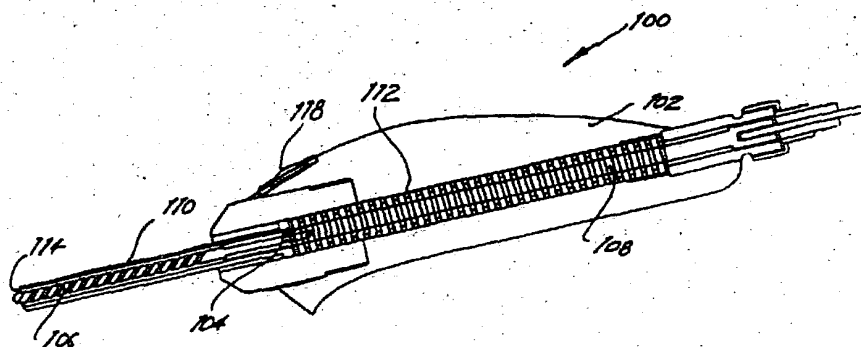
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(54) Title: A DRIVER



(57) Abstract

A driver (100) for use in orthopaedic surgery or the like having a generally elongate housing (102) adapted for single-handed gripping operation. The driver includes engagement means (104) associated with the housing for releasably engaging the proximal end of a longitudinally extending driven member and includes drive means, such as a flexible drive spindle (108), for rotatably driving the engagement means. The driver further includes shield means (110) that are supportingly connected with an end of the housing so as to extend co-axially with and fully circumscribe the driven member. The distal end of the shield means (110) terminates in an end portion (114) adapted to be placed against the surface into which the member is driven. The driver also includes means to permit relative movement in an axial direction between the engagement means (104) and the end portion (114) for advancement into and retraction from the surface so that, in use, single-handedly, the driven member (106) is always fully shielded and supported. In the preferred form of the invention the relative movement between the engagement means (104) and end portion (114) is achieved by means of a longitudinally retracting shield (110). In other embodiments the shield is fixed and the engagement means are advanced internally within the housing.

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TITLE: A DRIVER

FIELD OF THE INVENTION

The present invention relates to a single handed power driver with integral shield mechanism for drilling and inserting fasteners such as screws and the like.

5 The invention has been developed primarily for use in orthopaedic surgery and will be described hereinafter with reference to this application. However, it will be appreciated that the invention is not necessarily limited to this particular field of use.

BACKGROUND OF THE INVENTION

Orthopaedic surgery often involves the joining of two or more segments of a
10 bone. This join is usually accomplished by bolting, screwing or wiring the segments directly together, or bolting, screwing or wiring the segments to a common plate or other intermediate joining member. It is normally necessary to use some form of powered driver to drive a drill bit, screws, Kirschner wire or other device or implement into the bone to facilitate the join.

15 The positioning of the bolts, screws or wires in the bone is extremely critical for the integrity of the joint and the subsequent healing process. Accordingly, in addition to the usual complications and stress generally associated with overall patient well being in surgery, the orthopaedic surgeon also has to ensure the driver is very accurately positioned. This is difficult as it often requires holding the bone segments
20 to be fixed in an exact orientation whilst simultaneously aiming, supporting and operating the driver.

To assist in overcoming these problems, a separately supportable drill guide plate or similar is initially positioned adjacent the bone or prosthesis being drilled in

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order to ensure that the drill bit or similar passes into the bone at the desired location and on the desired course. Ideally, the guide plate also serves to minimise damage to the soft tissue surrounding the bone which may get caught by the rotating drill bit, screw or wire.

5 It will be appreciated that the above procedure requires the surgeon to hold in position the fragments to be fixed whilst simultaneously using the power drill and positioning and holding the drill guide. Clearly, this is something that is difficult, if not impossible to achieve with any accuracy with only two hands, so often the surgeon has to depend on the help of an assistant. However, this is not only labour intensive
10 but is rarely satisfactory, as the assistant is not generally in a position to maintain or judge correct alignment and their presence may even restrict access to and/or sight of the surgical opening.

To further complicate matters, the prior art procedures often require use of a separate tool to increase and/or determine the depth of travel of the drill or other
15 driven member.

It is an object of the invention to overcome or at least ameliorate one or more of these deficiencies of the prior art or at least offer a useful alternative thereto.

DISCLOSURE OF THE INVENTION

According to a first aspect of the invention there is provided a driver for use in
20 orthopaedic surgery or the like, the driver including:

a housing adapted for single handed gripping operation;

engagement means associated with said housing for releasably engaging the proximal end of a longitudinally extending driven member;

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drive means for rotatably driving the engagement means;

longitudinally extending shield means supportingly connected with an end of the housing so as to extend co-axially with and fully circumscribe said driven member, the distal end of said shield means terminating in an end portion adapted to be placed
5 against the surface into which the member is to be driven; and

means to permit relative movement in an axial direction between said engagement means and said end portion for advancement into and retraction from said surface so that, in use, single handedly, the driven member is always fully shielded and supported.

10 Desirably, the shield means is sized to also act as a guide for the driven member. However, in some embodiments the shield means may include separately identifiable guide means at or adjacent the end portion of the shield.

The driven member may be a drill bit, screw, Kirschner wire or other surgical implement, tool or device. Preferably, the device is configured such that the distal
15 point of the driven member in the inoperative mode protrudes slightly from the shield means to facilitate accurate positioning prior to driving and is, ideally, retractable, relative to the end portion, prior to operation.

The driven member may directly engage the engagement means such as in the case of a drill bit. Alternatively the driven member may engage an intermediate
20 member that directly attaches to the engagement means such as in the case of an intermediate bit to engage a screw.

In a first preferred form of the first aspect, the engagement means are generally fixed relative to the housing and the shield means are retractable into said housing as

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the driven member is advanced into the surface. Preferably, the shield means is retractable against a biasing means such that as the driven member is advanced or retraced by movement of the housing, the shield means is urged into maintained contact against the surface into which the member has been driven. In another form, 5 the shield means comprises two or more cylindrical concentric telescoping portions that decrease in diameter towards the end portion.

Desirably, in this first preferred form the shield means comprises a generally cylindrical member, which, preferably, is marked externally with gradations indicative of the penetration depth of the driven member beyond the shield end portion. In 10 another preferred form the depth indication is provided via a direct window on the housing or via a display coupled to an electronic displacement transducer.

This first embodiment provides an elegantly simple solution to the prior art problems, enabling the driver to be advanced by applying a linearly acting driving force to the housing which drives in the member and simultaneously overcomes the 15 biasing force on the shield. In this manner the drill can be accurately positioned and guided and the soft surrounding tissues protected from damage by the shield, the retraction of which also directly or indirectly provides an indication of depth of penetration. All this is achieved with a compact unit that requires only one handed operation.

20 According to a second embodiment of the first aspect of the invention, the shield means is rigidly connected to or forms part of the housing and the engagement means are adapted to move internally relative to the housing between a retracted position in which the driven member is substantially located within the shield means and an

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extended position in which a part of the driven member protrudes from the shield means as it is driven into the surface.

In this second embodiment a plurality of changeable shield portions may be provided for use with the driver. The bore of the guide means in each of the shield means may be produced in one of a range of diameters to receive different diameter driven members. A supporting clearance fit is generally provided between the bore of the guide and the driven member. However, in some cases where the driven members have sufficient rigidity, one shield of, for example, 4.5mm internal diameter is suitable for use with all drills and wires under, say, 4.0mm.

10 In both embodiments, the drive means preferably includes a first motor which is desirably electrically or pneumatically powered. The first motor may be internal or external the driver. Preferably, in the first embodiment the motor is external.

In one variation of the second embodiment the driver includes a telescopic coupling operatively connecting an internal first motor to the engagement means. In 15 this embodiment the motor is fixed relative to the shield means and the engagement means travels along the rotational axis of the driven member to move the driven member between the retracted and extended positions. In another variation of the second embodiment the internal first motor and the engagement means travel along the rotational axis together.

20 Alternatively, in either embodiment, the first motor may be external the drill with a flexible coupling, such as a cable drive, operatively connecting the first motor to the engagement means.

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The first motor may, in the second embodiment, be adapted to both rotationally drive the engagement means and extend and retract the engagement means and hence the driven member.

In an alternative arrangement of the second embodiment the first motor drives
5 the engagement means only and a second motor is adapted to extend and retract the drill bit.

The drill of the second embodiment may include gear means operatively connected to the any or all of the motor or motors or engagement means for extension and retraction of the engagement means. The gear means may include selectively
10 operable advancement and retraction gears for extending and retracting the engagement means. In other embodiments a single gear is used with a bi-directional motor.

In further variations of the second embodiment the engagement means may be advanced and retracted manually.

15 . . . Optionally, means can also be provided to give an external indication as to travel of the engagement means which in this second embodiment is indicative of depth of penetration of the driven member.

The driver may also include a variable speed gearbox between the first motor and the engagement means. Alternatively the first motor may be a variable speed
20 motor. If desired, the first motor also provides a fixed slow speed.

In all embodiments the engagement means is preferably a female/male connector adapted to engage a corresponding male/female connector provided on the driven

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member. The engagement means can also include other types of connectors such as snap-lock fittings or chucks.

In one form the female connector and the proximal end of the driven member preferably include a recess and a correspondingly shaped spigot respectively. In other
5 embodiments the recess and spigot have square, triangle, hexagonal or star shaped cross sections. The recess and spigot may, alternatively, include mating threads.

The driver may also include a plurality of different sized engagement means to cater for different sized driven members. In an embodiment the driver includes a magazine adapted to hold a plurality of driven members having commonly sized drive
10 head portions, the magazine being adapted to permit rapid engagement of the individual driven members with the engagement means. Desirably, the magazine holds a plurality of like driven members of different size or a selection of different complementary driven members.

In one version of the second embodiment, the driver housing, which is attached
15 to or includes the shield and optional guide portion, is adapted to encase the engagement means. The housing preferably includes external manual controls for the driven member rotation, advancement and retraction of the driven member. The manual controls are preferably positioned on the housing for left or right hand manipulation. The driver may alternatively or additionally include remote controls.

20 The driver may be configured such that the driven member extends and remains in contact with the surface a short distance from the end portion so as to permit the driven member to engage the surface and thereafter drive itself into the surface. This configuration is applicable when the driven member is, for example, a self tapping

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screw which, when rotated, will continue to advance itself after initial engagement is made with the surface.

The driver may also be configured to continually advance the driven member into the surface. This configuration is applicable when the driven member is, for example, a drill bit which needs to be both rotated and advanced to drive it into the bone or similar surface.

Desirably, the end portion of the shield includes means, such as serrations or spikes, to help prevent the tip of the driver from "wandering" once in contact with the relevant surface.

10 According to a second aspect of the invention there is provided a plurality of driven members of various type and size each having at their proximal ends a common sized and shaped head portion for engagement with correspondingly sized drive coupling.

According to a third aspect of the invention there is provided an adaptor for a driven member comprising at one end a standard sized and shaped head portion for engagement with a correspondingly sized drive coupling, said adaptor being configured at said other end remote said first end for torque transmitting attachment to a driven member of varying size.

20 Preferably, the adaptor is made of a plastics material or the like, the torque transmitting attachment to said driven member being achieved, for example with drill bits, by moulding onto an end of said driven member that either incorporates a driving flat or has been flattened or roughened to reduce the likelihood of rotation within the adaptor. In the case of screws or the like, the torque transmitting attachment is via a

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suitable shaped drive portion selected to correspond with the drive recess provided in the head of the screw.

Desirably, the head portion of the second and third aspects is a standard shape such as round, hexagonal, square, d-shaped or the like. With the round head portion a standard chuck may comprise the drive coupling. In the other variations where the head portion may have a square or hexagonal cross section, it is preferable the drive coupling is correspondingly sized and shaped.

Preferably, the driver according to the first aspect of the invention includes an engagement means sized and configured to receive driven members according to the second aspect of the invention or driven members incorporating adaptors according to the third aspect of the invention.

Desirably, the driver is of a general pencil-style shape. However, other configurations, including a pistol-style arrangement, are possible.

BRIEF DESCRIPTION OF THE DRAWINGS

Preferred embodiments of the invention will now be described, by way of example only, with reference to the accompanying drawings in which:

Figure 1 is a first embodiment of a fixed shield driver according to the first aspect of the invention with the driven member in the extended position;

Figure 2 is a partial view of the driver shown in Figure 1 with the driven member in the retracted position;

Figure 3 is a sectional side view of a second embodiment of a fixed shield driver according to the first aspect of the invention;

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Figure 4 is an enlarged view of a telescopic coupling used in the driver of Figure 3 in extended and retracted positions;

Figure 5 is a partial sectional side view of a third embodiment of a fixed shield driver according to the first aspect of the invention;

5 Figure 6 is an exploded perspective view of a fourth embodiment fixed shield driver according to a first aspect of the invention;

Figure 7 is an internal perspective view of a fifth embodiment fixed shield driver according to a first aspect of the invention;

Figure 8 is a telescopic coupling for use with the driver shown in Figure 7;

10 Figure 9 is a diagrammatic end view of a gear assembly for use with the driver shown in Figure 7 with the advancing gears engaged; and

Figure 10 is a diagrammatic cross-sectional end view of the gears shown in Figure 9 with the retraction gears engaged;

Figure 11 is a diagrammatic perspective view of a first embodiment retracting shield driver according to the first aspect of the invention;

Figure 12 is a schematic sectional view of the driver shown in Figure 11;

Figure 13 is a side view of the driver shown in Figure 11;

Figure 14 is a top plan view of the driver shown in Figure 13;

Figure 15 is an inverted plan view of the driver shown in Figure 13;

20 Figure 16 is a front end view of the driver shown in Figure 13;

Figure 17 is a rear end view of the driver shown in Figure 13;

Figure 18 is a part view of the driver shown in Figure 11 illustrating the shield in the retracted position during use;

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Figure 19 is a schematic representation of how the retractable shield driver operates with a screw and intermediate drive adaptor;

Figure 20 illustrates examples of quick release drive coupling suitable for use with drivers of the first aspect of the invention and driven members in accordance with
5 the second and third aspects of the invention;

Figure 21 is a schematic part view of an alternate telescoping shield arrangement for use with the retractable shield driver according to the first aspect in the invention;

Figure 22 is a schematic representation of a full driver and driven member kit in accordance with the invention; and

10 Figure 23 is a schematic view of a surgical opening made in preparation for a bone chilling operation using the drivers hereinbefore described.

PREFERRED EMBODIMENTS OF THE INVENTION

Preferred embodiments of fixed shield drivers according to the invention will now be described with reference to Figures 1 to 10 of the accompanying drawings.

15 Referring firstly to Figures 1 and 2, there is shown a preferred pencil-style driver 10 for use in orthopaedic surgery or the like. The driver includes a shield portion 12 having a bore 14 surrounded by an adjacent guide portion 15 sized and adapted to receive a driven member in the form of drill bit 16. The shield terminates in a distal end portion 18 which is adapted to be placed against the surface into which the drill is
20 to be driven. The driver 10 also has an engagement means in the form of female connector 20 for releasably engaging the driven end 22 of the driven member 16.

A drive means, in the form of electric motor 24, is used to rotate the engagement means 20 and drill bit 16. The connector 20 is coupled to the motor 24 by a drive

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shaft 26. The drive shaft 26 is rotated by the motor 24, and is also able to slidably pass through motor 24 in the direction of longitudinal axis 25. The end 27 of the drive shaft opposite the connector is connected to second motor 28.

The driver has a generally cylindrical body 30 of which shield portion 12 forms
5 an integral part. The distal end 31 of the body 30 contains an internal gear form 32 adapted to engage the external gears 33 of the second motor 28.

The bore 18 of the guide portion of the shield 12 is sized as a clearance fit around the outer diameter of the drill bit 16. A number of interchangeable shield portions having correspondingly sized bores are provided to accommodate various
10 sizes of drill bits, screws, wire or the like. However, depending on the stiffness of the driver members, one shield/guide size may be adequate for a range of driven members.

The female connector 20 includes a recess 35 and the proximal end 22 of the drill bit has a correspondingly shaped spigot 36. In this embodiment the recess and spigot have a square cross-section. It will be appreciated that various other cross-
15 sections may be used and they may include snap-lock fittings or similar to provide a secure releasable connection between the connector and the drill bit.

The body 30 also includes external manual controls (not shown) to allow the surgeon to control the speed of the drill bit rotation, advancement and retraction. Remote controls, such as foot pedals (not shown) are also available for use with the
20 driver 10. Electrical power for the driver is supplied through a cable 34.

In use, the spigot 36 of the drill bit is inserted into the recess 35 of the connector 20. The second motor 28 is then used to position the engagement means such that the distal end 18 of the drill bit is within the guide portion 12. This is achieved by

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energising the second motor 28 and thereby rotating the gears 33 causing the second motor to travel in the direction of the axis 25. As the drive shaft length is fixed, the translational travel of the second motor 26 results in identical translational travel of the female connector 20 and the drill bit 16. The end 18 of the guide portion is then
5 placed adjacent the bone or other apparatus into which the surgeon intends to drive the drill bit. The surgeon then uses the first motor 24 to rotate the drill bit and the second motor 26 to advance it from within the guide and extend the drill bit into the bone or other surface.

The driver according to the invention obviates the need for the surgeon to
10 manipulate and position a separate guide plate and therefore provides a simplified surgical procedure with more accurate positioning of the drill bit or the like. In particular, the driver allows accurate positioning of the drill bit whilst still providing a shield and/or guide so as to overcome the difficulties associated with driving through soft tissue and the like.

15 If a screw is driven instead of a drill bit, then an intermediate member (not shown) may be needed which has one end adapted to connect to the connector 20 and another adapted to releasably engage the screw head.

Figures 3 and 4 show a second embodiment of a fixed shield driver according to the invention in which like numerals will be used to designate corresponding features.

20 In this embodiment, a telescopic coupling 40, comprised of square cross-section inner and outer portions 40 and 42 respectively, is connected to the drive shaft 28 intermediate the motor 24 and the connector 20. Internal gears 46 are provided in the body 30 forward of the motor and are engaged by a worm gear 48 attached to the drive

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shaft. In this way, rotation of the drive shaft by the motor 24 causes the drill bit 16 to rotate about the axis 25 and also translate along the axis 25 as the worm gear 48 is driven along the gears 46. The movement of the connector 20 relative to the motor 24 is accommodated by the telescopic coupling 40, as exemplified in the two extreme positions shown in Figure 4. The pitch of the gears 46 permits optimisation of the relationship between the rotational speed of the drill bit and its translational advancement and retraction into the bone or other surface.

Turning now to Figure 5 there is shown a third embodiment of a fixed shield driver according to the invention in which like numerals will again be used to designate corresponding features.

In this embodiment, the distance between the first motor 24 and the connector 20 is fixed by coupling 50. The body 30 includes an internal rack gear 52 engaged by a worm gear 54 coupled to second motor 26. The second motor is mounted to the rear of the first motor 24.

Rotation of the worm gear 54 causes it to travel along rack 52, simultaneously translating the first and second motors, the connector 20 and the drill bit 16.

The third embodiment of the fixed shield driver according to the first aspect of the invention also includes a replaceable stepped guide portion 58 which is a press or snap lock fit into the distal end 60 of driver body 30.

A fourth embodiment of fixed shield driver is shown in Figure 6. This embodiment also includes a second motor 26 coupled to the rear of first motor 24 and uses a worm gear 62 to advance and retract the motor along gears 64. The external circumference of the drive motor 24 is provided with ridges 66 which are configured

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to slide along correspondingly shaped recesses 68 provided in the two halves of the drill body 70 and 72. This embodiment also includes a stepped guide 74 with a replaceable bore section 76. The replaceable bore section 76 allow the internal diameter of the guide bore to be altered whilst leaving the guide itself in place. The drill bit 78 includes an annular recess 80 adapted to snap lock into the connector 20.

Turning now to Figures 7 and 8 there is shown the internal components of a fifth embodiment fixed shield driver encased by the driver body 30 shown in phantom. In this embodiment, the first motor 24 is directly attached to the end of the connector 20. The other end of the motor is fixed in relation to a gear mechanism 82 connected to a second motor 84 by a telescopic coupling 86. The gear mechanism 86 includes an opposed pair of advancement gear racks 88 and an opposed pair of retraction gear racks 90.

The second motor 84 rotates the worm gear 92 which can be selectively engaged by one of the opposed pairs of gear racks 88 or 90. The racks are surrounded by a spring steel casing 94, best shown in Figures 9 and 10, which deforms under digital pressure to bring one of the gear sets into engagement with worm gear 92.

As shown in Figure 10 when digital pressure is applied to the retracting gear set 90 they are brought into engagement with worm gear 92 and rotation the worm gear causes the first motor, the connector and a tap 96 to retract into the guide 12.

Similarly, if the advancement gear tracks are pressed into engagement with worm gear 92 then the same directional rotation of the motor will cause the first motor 24, the connector 20 and the tap 96 to advance and protrude from the end of the guide.

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In a variation of this embodiment only a single opposed pair of gear racks are used and a switch is provided to reverse the direction of the second motor 26 in order to selectively advance or retract the connector 20 and associated equipment.

In further embodiment of the driver (not shown) the motor is fixed relative to the connector and is able to be manually translated within the drive body. This embodiment has particular application in the driving of self-tapping screws and the like which advance themselves into the bone after initial engagement is made as the connector and accompanying motor are drawn forward by the screw due to the self-tapping action.

10 A preferred embodiment of the retractable shield driver according to the first aspect of the invention will now be described with reference to Figures 11 to 22 of the accompanying drawings.

The primary difference between this embodiment and those previously illustrated and discussed above, is that no separate mechanism is provided for
15 advancing the engagement means relative to the housing. Instead, the advancement is achieved by applying a linearly acting load to the driver, the shield being configured to retract into the housing as the driven member advances, thereby ensuring that the surrounding soft tissue is protected at all times.

This is a very simple solution that provides excellent feel for the operator as well
20 as providing a direct visual indication of the penetration of the driven member, either directly by means of the retracting shield, or, via a window or electronic indicator on the housing itself. These features are described in more detail below.

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Turning first to Figures 11 and 16, it can be seen that the driver 100 once again has a generally elongate housing 102 that is contoured and otherwise adapted for single handed gripping operation. Engagement means, shown generally at 104, are provided within the housing for releasably engaging the proximal end of a
5 longitudinally extending driven member such as the drill bit 106 shown. Drive means are again provided for rotatably driving the engagement means which, in the embodiments shown comprises a flexible drive shaft 108 which is externally driven by an electrical pneumatic motor 128 (see Figure 22).

The driver 100 also includes a generally cylindrical retractable shield 110 which
10 is biased outwardly from the housing by means of a captive compression spring 112. The end portion 114 of the shield 110 is preferably serrated or includes spikes thereon to grip the bone surface to be drilled in order to prevent the drill from wandering during use.

In the embodiments illustrated, the generally cylindrical shield 110 is marked
15 with gradations 116, such that as the shield retracts telescopically within the housing 102 the operator is provided with a visual indication as to the effective penetration depth of the drill 106. In other embodiments the depth indication is achieved via a window provided in the housing which shows a marker on the shield 116 retracting into the housing against an appropriate scale. Other more sophisticated versions may
20 include some form of electrical or electronic display responsive to an appropriate displacement transducer.

One preferred shape of the driver housing 102 is shown most clearly in the orthogonal views depicted in Figures 13 to 17. In this particular arrangement the

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on/off button 118 is conveniently located on the upper portion of the housing at or adjacent the location at which the operator's index finger would rest during use. In other embodiments, not shown, the on/off mechanism is remote from the driver housing 102 and may be, for example, foot operated.

5 Turning next to Figure 20 there is shown a range of quick release coupling arrangements suitable for use with various embodiments of the drivers previously illustrated. The left most design illustrates a spring-ball type connector; the centre design shows a tapered hexagonal sectioned male drive and corresponding hexagon female socket; and the right most design shows a standard tapered chuck type
10 coupling.

It will be appreciated that with the previously described retractable shield drivers, either long drill bits or other driven members will be required because of the retraction of the rigid shield 110 into the housing body, particularly if a conventional chuck device is used as the engagement means, or an engagement means must be used
15 which has an overall diameter that is less than the internal diameter of the shield. In the latter case, preferred narrow style engagement means include preferably slightly tapered male driver connectors having appropriate drive flats that are adapted to frictionally engage correspondingly shaped female recesses in the proximal end portions of the driven members.

20 These problems are ameliorated in one alternate embodiment by use of a collapsible shield configuration as shown in Figure 21 which comprises a plurality of telescoping cylindrical portions 111 which progressively nest one within the other as the driver advances against the surface. Accordingly, when the shield is in the fully

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retracted position, it extends into the housing only a fraction of it's overall extended length, thereby enabling shorter drill bits and the like to be used without placing undue constraints on the overall diameter of the chuck device/engagement means.

Turning next to Figure 22, there is shown a preferred full driver and driven member kit in accordance with the invention. The kit illustrated includes the retractable shield driver 100 mounted on a support rack 120 adjacent a set of various drilling members 122. The rack includes a fixed upper surface 124 and a selectively releasable gripping mechanism shown generally at 126. Separately mounted at some convenient location is a main drive motor 128 from which extends the flexible drive cabling 130 which attaches to the rear end of the driver 100.

In use, for example, the wound adjacent a bone to be drilled would be opened as shown in Figure 23. The driver, having been pre-loaded with the appropriate drilling member, would then be taken in one hand and the end of the drill protruding from the end portion 114 would be accurately positioned on the bone 132. The tip of the drill member is then retracted relative to the end portion 114 of the shield 110 by either letting out the shield against the biasing spring from a partially retracted starting position until it hits the surface or alternatively by applying pressure to the driver so that the engagement means 104 retracts a short predetermined distance by a suitable mechanism so that again the end portion 114 comes into contact with the bone.

The driver can then be actuated directly or indirectly and the drill 106 advanced into the bone by applying a linear force to the housing 102. Once the drill has reached the predetermined depth as indicated on the shield or other depth indication device, the driver housing can be retracted, the biasing spring 112 keeping the shield closely

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adjacent bone at all times thereby preventing the soft tissue from getting entangled in the rotating drill bit (see for example Figure 18).

In the event that the operation requires a further separate drilling operation or the like be performed, the driver is simply returned to the rack 120 in alignment with a
5 vacant driven member location as shown. Preferably the rack has been configured such that the shield 110 will not be able to pass through the apertures formed in the upper surface 124. This enables the driver to be pushed down in a manner whereby the shield 110 is retracted into the housing 102 and the driven member is exposed. When the distal end of the driven member has been lowered sufficiently, the gripping
10 means 126 (which may comprise any suitable device) is actuated such that the drill bit is firmly held. The driver 100 is then retracted, thereby pulling the drill bit from the quick release coupling. The driver is then advanced to the station that holds the next desired drill member, the drive end of the driven member simply clicking into connection with the engagement means of the driver. First making sure that the
15 gripping mechanism 126 has not been actuated, the driver and newly assembled driven member can then be released from the rack ready for operation. This procedure can be repeated as necessary, making the entire process fast, clean and accurate with no additional assistance being required.

When it is desired to use the driver to insert a screw or the like, an intermediate
20 adaptor 134 is used such as is shown in Figure 19. The adaptor has one end adapted for releasable connection to the engagement means and the other adapted for driving the screw.

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In the preferred forms of the retractable shield driver according to the invention, a high torque reasonably low fixed speed drive is provided. However, it will be appreciated that other variations are possible with different fixed speeds or variable speed control as maybe required under different circumstances.

5 In many of the fixed shield embodiments described, the drivers are electrically powered by mains power introduced into the driver along cable 34. However, battery power may be used to reduce the hazard of a power cable trailing the driver during surgery. In other embodiments, particularly the retractable shield embodiments, pneumatic or hydraulic power is used.

10 Further, whilst generally pencil shaped housing configurations have been described, other embodiments include alternate configurations such as pistol-styled housings.

Although the invention has been described with reference to specific examples, it will be appreciated by those skilled in the art, that the invention may be embodied in
15 many other forms.

CLAIMS

1. A driver for use in orthopaedic surgery or the like, the driver including:
a housing adapted for single handed gripping operation;
engagement means associated with said housing for releasably engaging the
5 proximal end of a longitudinally extending driven member,
drive means for rotatably driving the engagement means;
longitudinally extending shield means supportingly connected with an end of the
housing so as to extend co-axially with and fully circumscribe said driven member, the
distal end of said shield means terminating in an end portion adapted to be placed
10 against the surface into which the member is to be driven; and
means to permit relative movement in an axial direction between said
engagement means and said end portion for advancement into and retraction from said
surface so that, in use, single handedly, the driven member is always fully shielded
and supported.
- 15 2. A driver according to claim 1 wherein the shield means is sized to also act as a
guide for the driven member.
3. A driver according to claim 1 wherein the shield means includes separately
identifiably guide means at or adjacent the end portion of the shield.
4. A driver according to any one of the preceding claims wherein the driven
20 member is a drill bit, screw, Kirschner wire or other surgical implement, tool or
device.
5. A driver according to any one of the preceding claims configured such that the
driven member in the inoperative mode protrudes slightly from the shield means to

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facilitate accurate positioning prior to driving and is retractable, relative to the end portion, prior to operation.

6. A driver according to any one of the preceding claims wherein the engagement means are generally fixed relative to the housing and the shield means are retractable
5 into said housing as the driven member is advanced into the surface.

7. A driver according to claim 6 wherein the shield means is retractable against a biasing means that urges the shield means toward the surface.

8. A driver according to claim 6 or claim 7 wherein the shield means comprises a generally cylindrical member.

10 9. A driver according to any one of claims 6 to 8 wherein the shield means comprises two or more cylindrical concentric telescoping portions that decrease in diameter towards the end portion.

10. A driver according to any one of claims 6 to 9 wherein the retractable shield means are marked externally with gradations indicative of the penetration depth of the
15 driven member beyond the shield end portion.

11. A driver according to any one of claims 6 to 9 wherein the depth indication is provided directly or indirectly on the housing by a suitable indication means responsive to the retraction of the shield means.

12. A driver according to any one of claims 6 to 11 wherein the drive means
20 comprises a flexible drive powered by a motor provided external to the housing.

13. A driver according to any one of claims 1 to 5 wherein the shield means is rigidly connected to or forms part of the housing and the engagement means are adapted to move internally relative to the housing between a retracted position in

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which the driven member is substantially located within the shield means and an extended position in which a part of the driven member protrudes from the shield means as it is driven into the surface.

14. A driver according to claim 13 wherein the driver is adapted to receive a
5 plurality of interchangeable shield portions for use with varying sized driven members.

15. A driver according to claim 13 or claim 14 wherein the drive means includes a first motor which is internal or external to the driver.

16. A driver according to claim 15 wherein the driver includes a telescopic coupling
10 operatively connecting an internal first motor to the engagement means, the motor being fixed relative to the shield means and the engagement means being configured to travel along the rotational axis of the driven member to move the driven member between the retracted and extended positions.

17. A driver according to claim 15 wherein the engagement means and an internal
15 first motor travel along the rotational axis together.

18. A driver according to claim 15 wherein the first motor is external to the drill and includes a flexible coupling operatively connecting the first motor to the engagement means.

19. A driver according to claim 15 wherein the first motor is adapted to both
20 rotationally drive the engagement means and to extend and retract the engagement means and hence the driven member.

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20. A driver according to claim 15 wherein the first motor rotationally drives the engagement means only and a second motor is adapted to extend and retract the engagement means and hence the driven member.
21. A driver according to anyone of claims 13 to 20 including gear means
5 operatively connected to any or all of the motors or engagement means for extension and retraction of the engagement means.
22. A driver according to claim 21 wherein the gear means includes selectively operable advancement and retraction gears for extending and retracting the engagement means.
- 10 23. A driver according to claim 21 utilizing only a single gear in combination with a bi-directional motor.
24. A driver according to any one of claims 13 to 18 wherein the engagement means are adapted to be advanced and retracted manually.
25. A driver according to any one of claims 13 to 24 including means to provide an
15 external reading indicative of depth of penetration of the driven member.
26. A driver according to any one of claims 21 to 25 including a variable speed gear box between the first motor and the engagement means.
27. A driver according to any one of claims 15 to 25 wherein the first motor is a variable speed motor.
- 20 28. A driver according to any one of the preceding claims wherein the engagement means is in the form of a chuck device adapted to receive a variety of sizes of driven members.

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29. A driver according to any one of claims 1 to 27 wherein the engagement means is preferably a snap-lock type or friction style connector adapted to receive driven members having commonly sized and shaped proximal end portions.

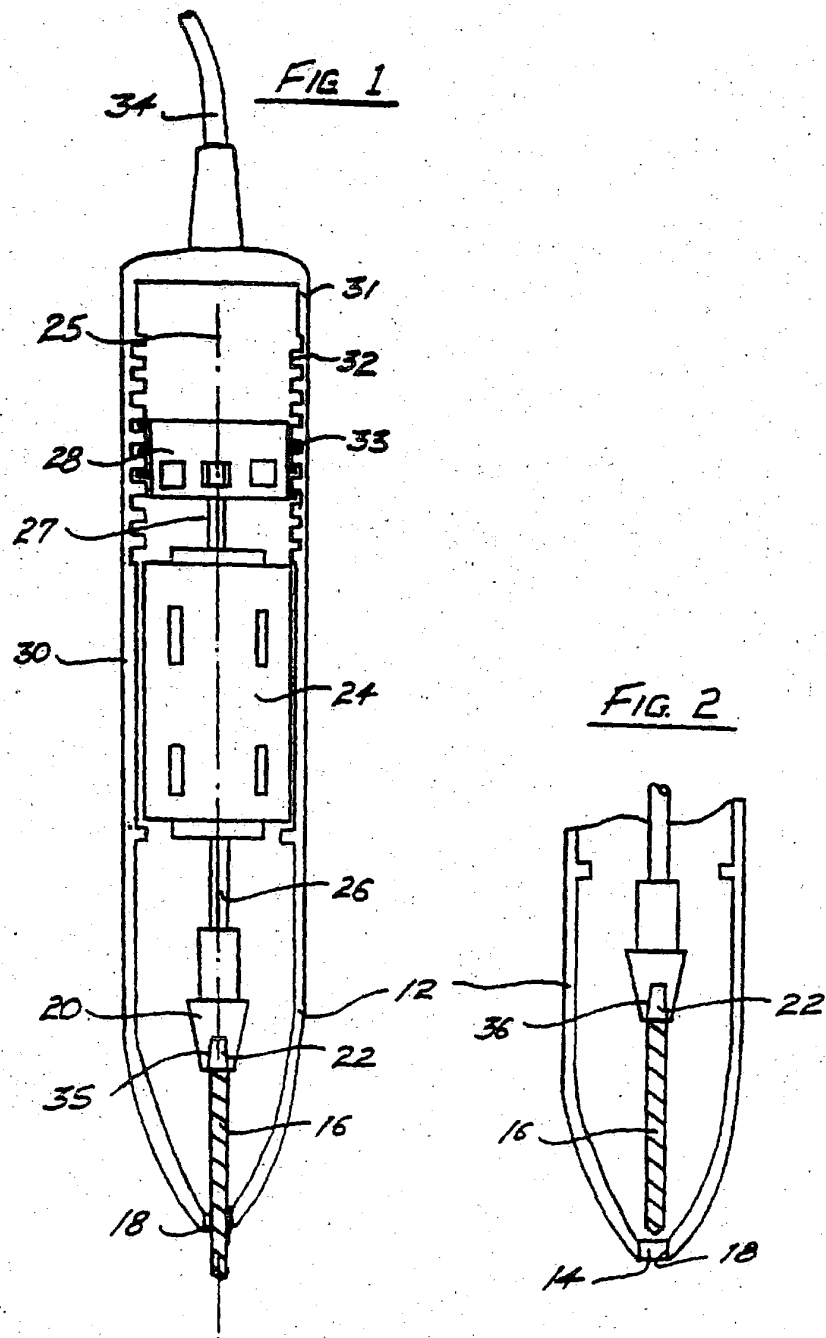
30. A driver according to any one of the preceding claims wherein the end portion of the shield includes a spike means to engage the surface into which the driven member is to be driven so as to prevent the driver from wandering.

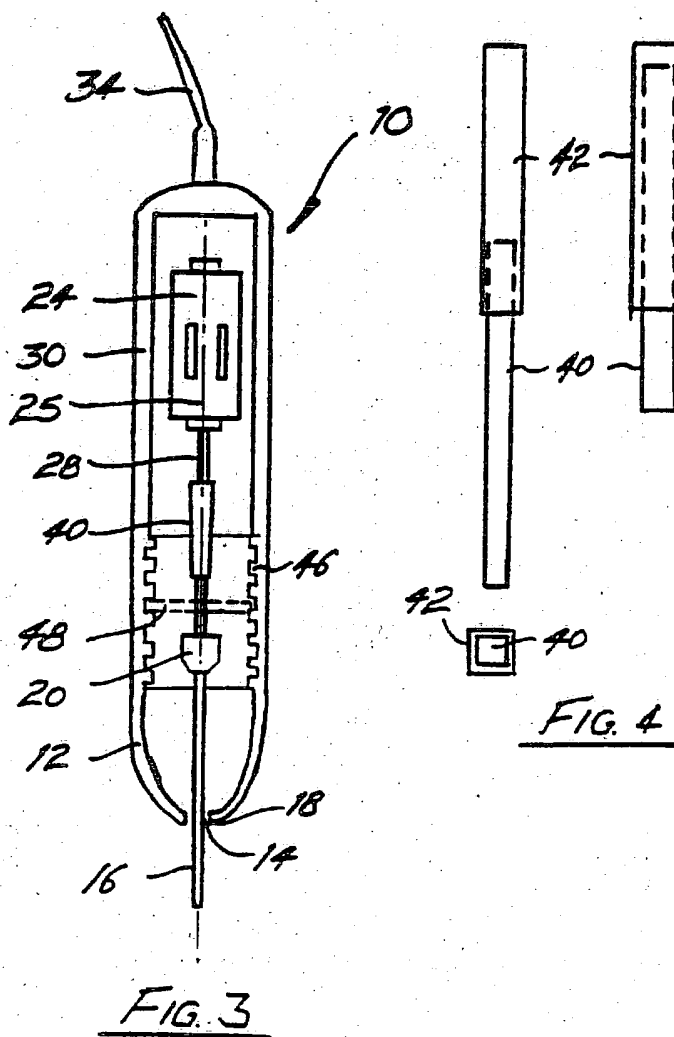
31. A plurality of driven members of various type and size each having at their proximal ends a common sized and shaped head portion for engagement with a correspondingly sized drive coupling.

32. An adaptor for a driven member comprising at one end a standard sized and shaped head portion for engagement with a correspondingly sized drive coupling, said adaptor being configured at said other end remote said first end for torque transmitting attachment to a driven member of varying size.

33. A adaptor according to claim 32 wherein the adaptor is moulded onto an end of said driven member that has been modified to provide some means for preventing or reducing the likelihood of rotation within the adaptor.

34. A driver according to any one of claims 1 to 30 including engagement means sized and configured to receive driven members in accordance with claim 31 or driven members having adaptors in accordance any one of claims 32 to 34.





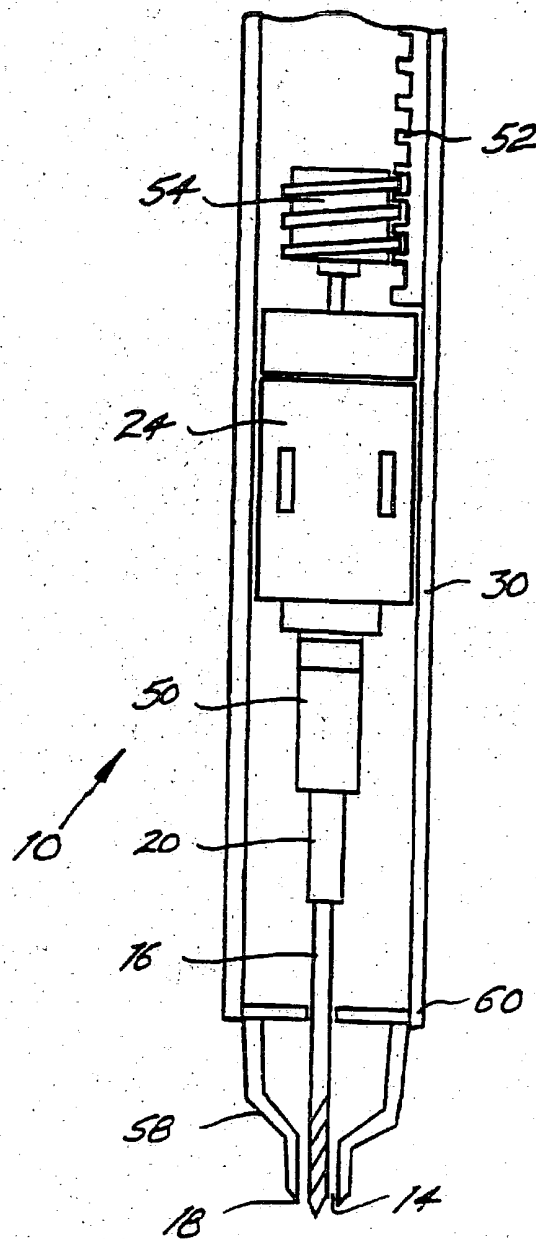
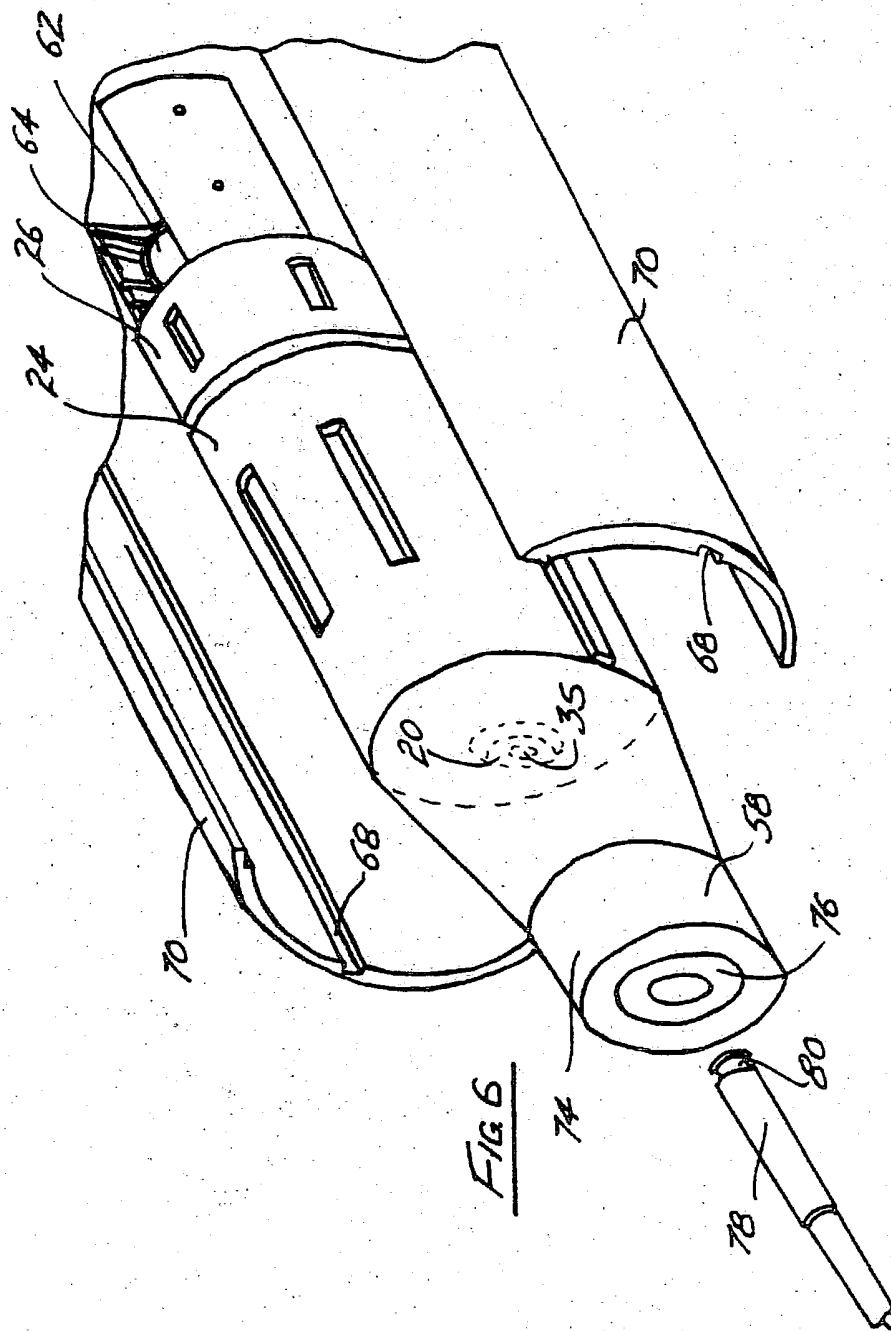
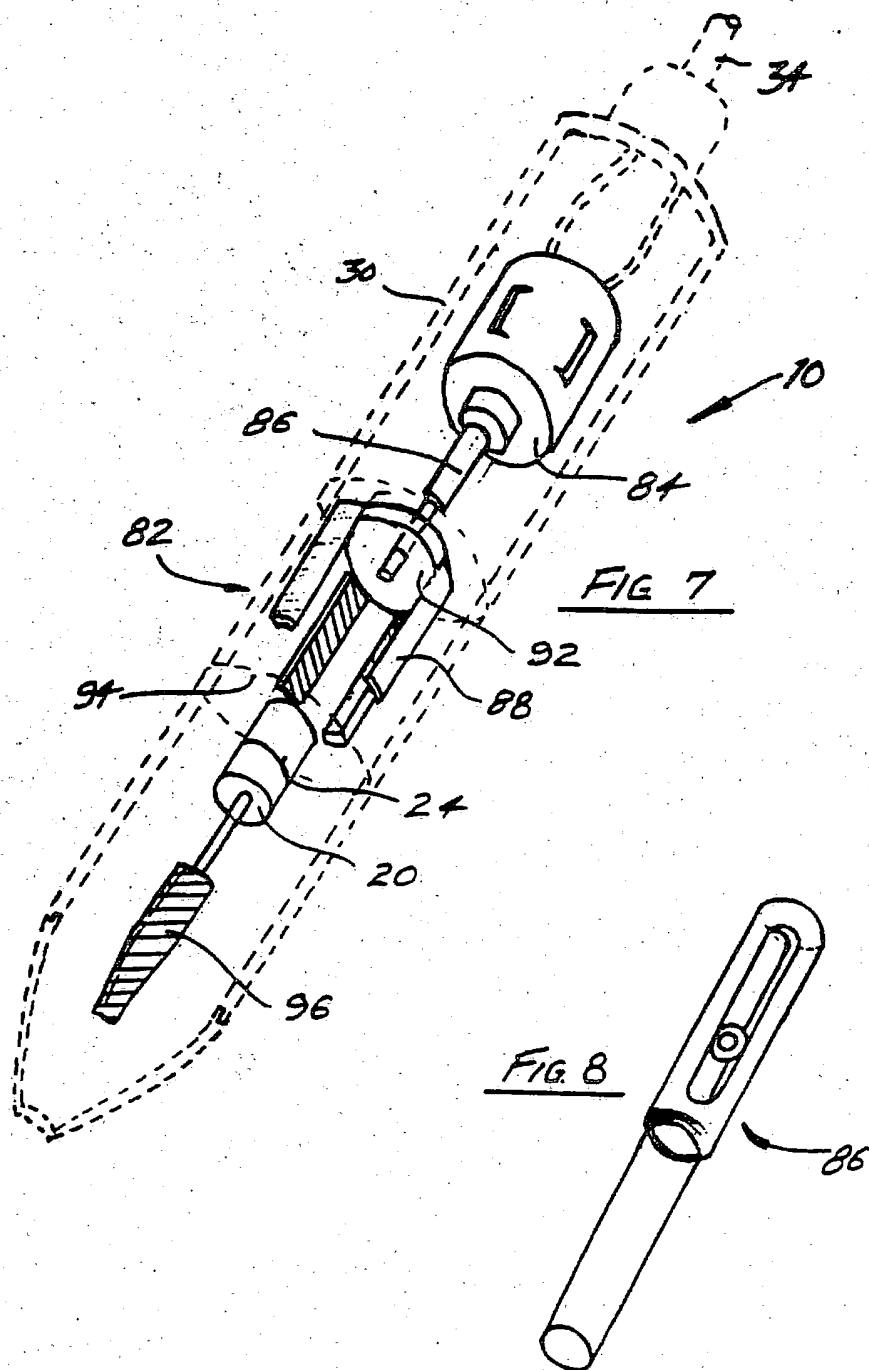


FIG. 5

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FIG. 9

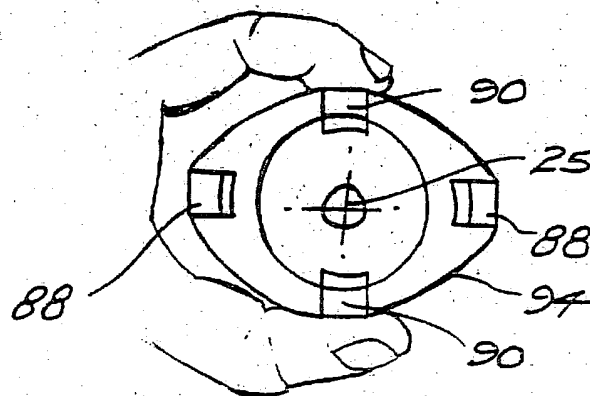
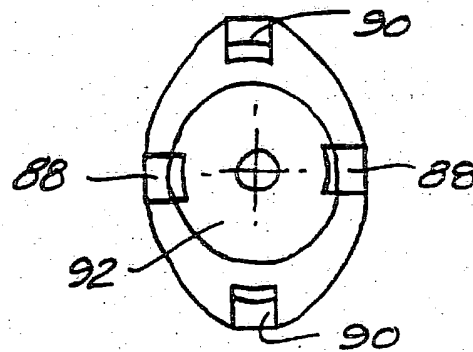
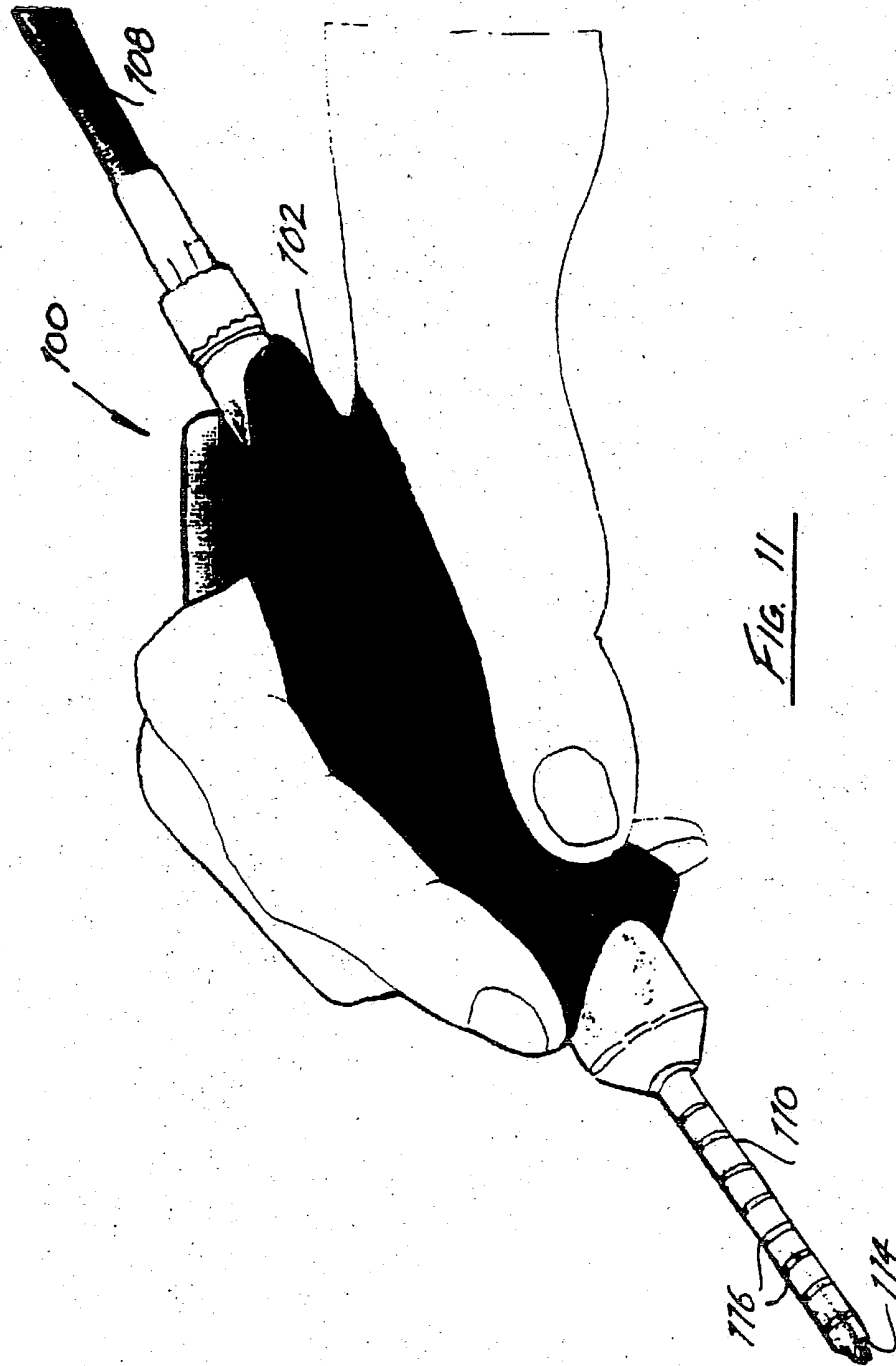
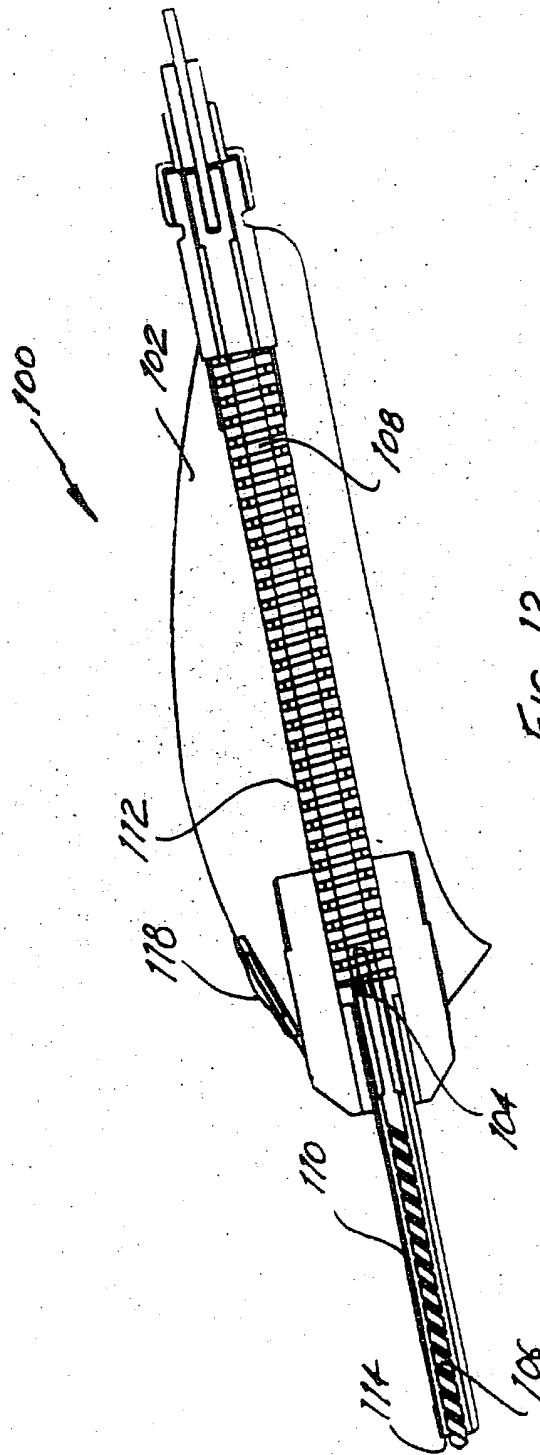


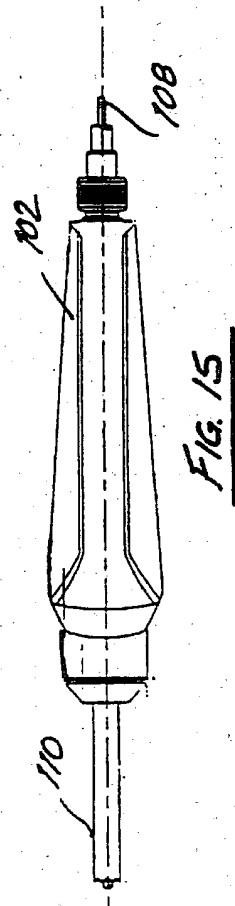
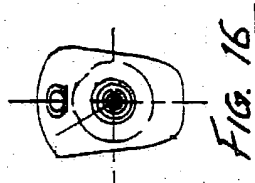
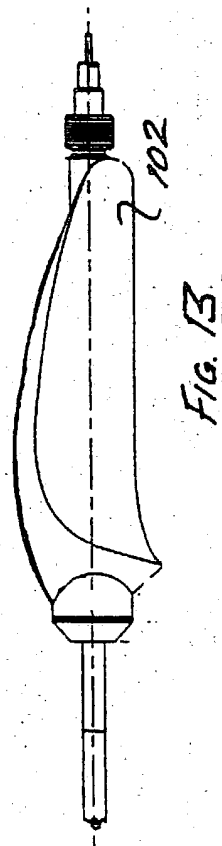
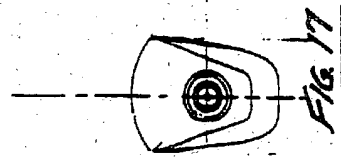
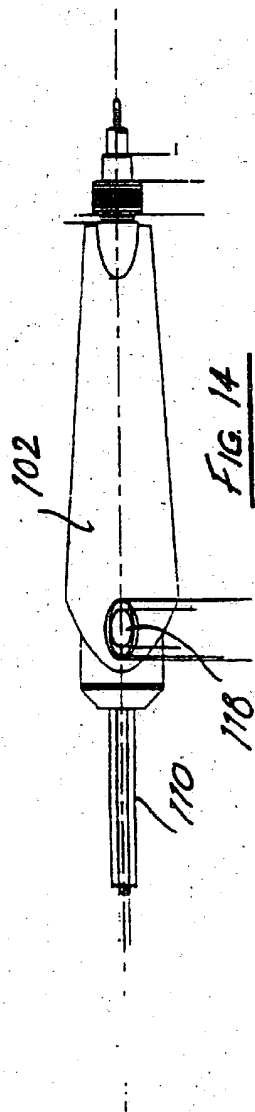
FIG. 10

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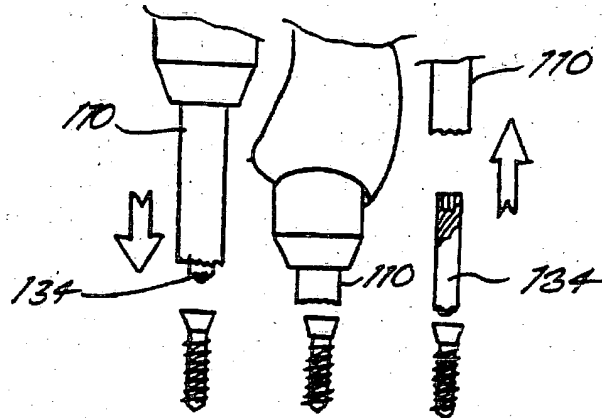
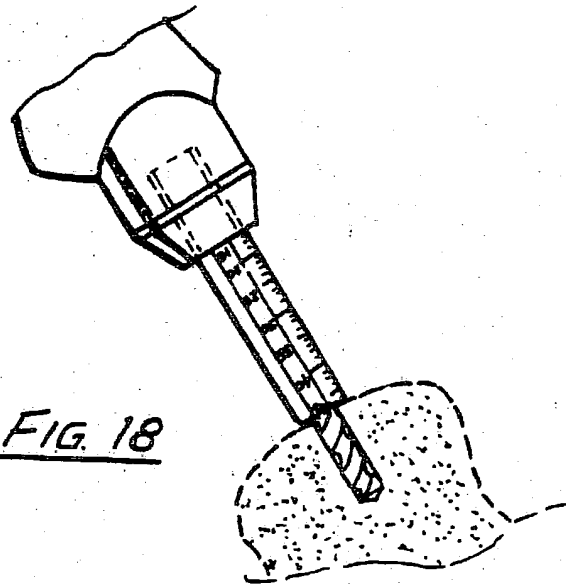




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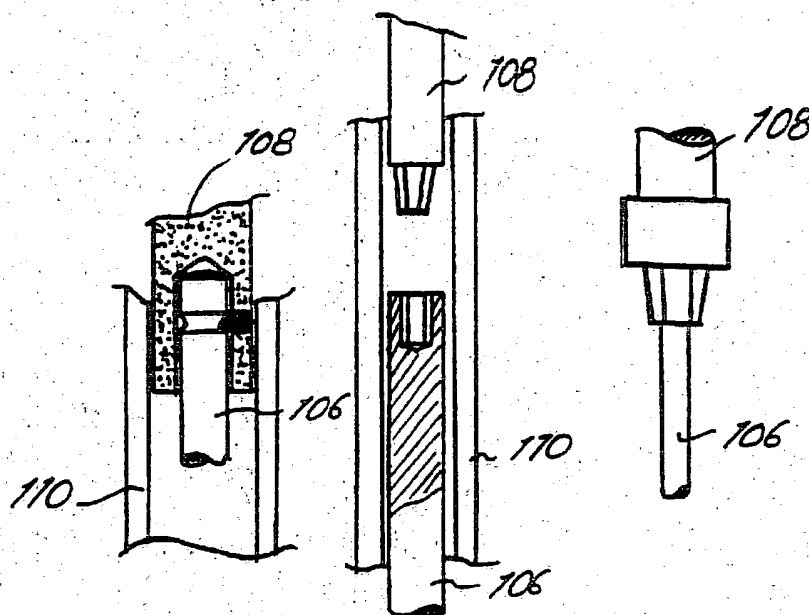
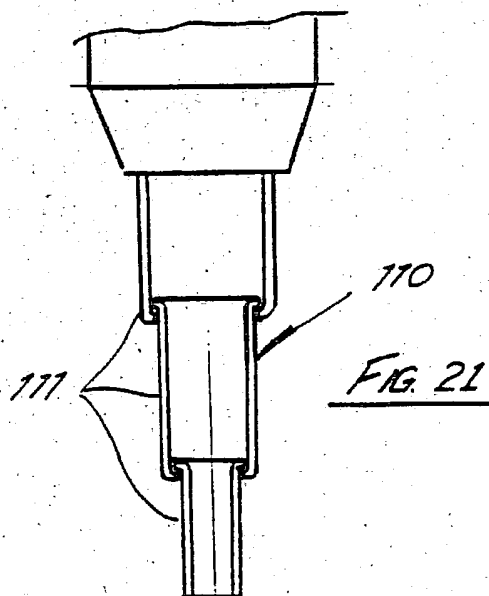


FIG. 20



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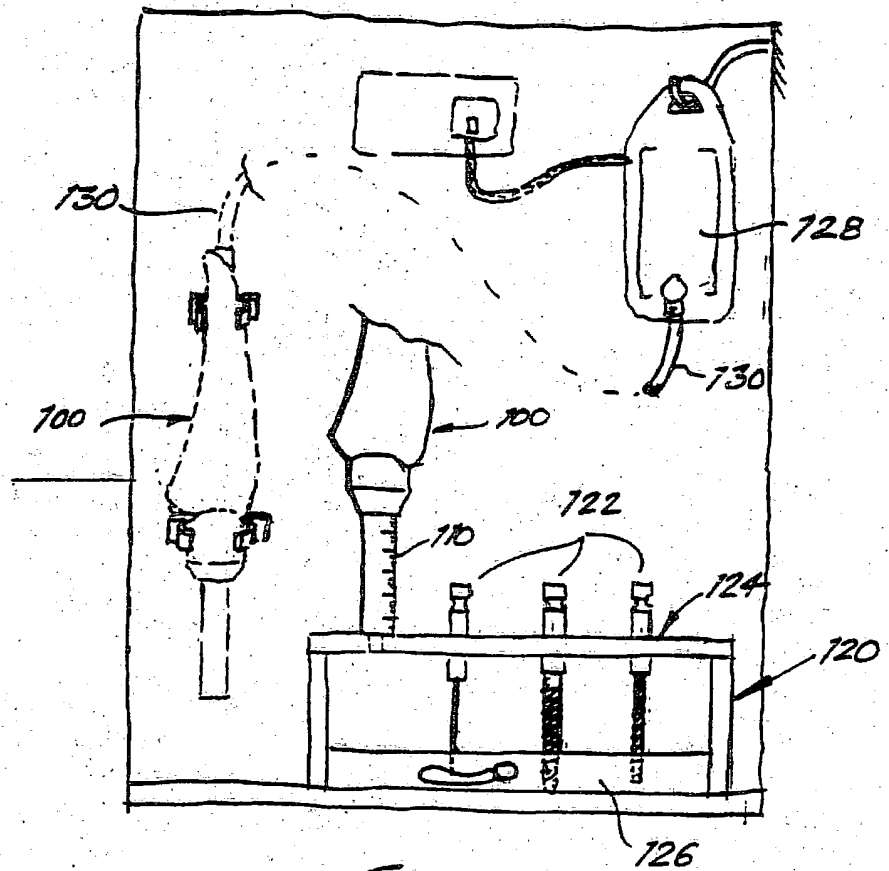


FIG. 22

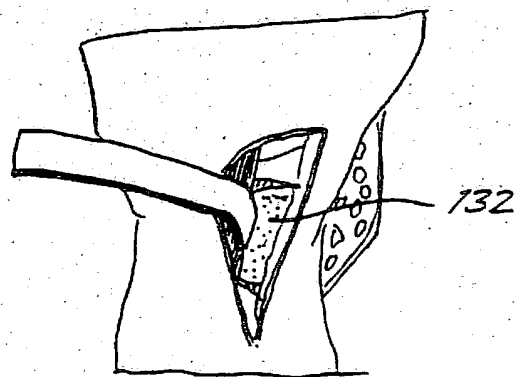


FIG. 23

INTERNATIONAL SEARCH REPORT

International Application No.

PCT/AU 96/00833

A. CLASSIFICATION OF SUBJECT MATTER		
Int Cl ^o : A61B 17/16, 17/17, 17/56 // B25B 13/56, 15/00, 23/00		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED		
Minimum documentation searched (classification system followed by classification symbols) IPC: A61B 17/16, 17/17, 17/18, 17/56, 17/58; B25B 13/56, 15/00, 23/00		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched AU: IPC as above		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) DERWENT JAPIO		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2526662 A (HIPPS) 24 October 1950 Column 2 line 44-column 3 line 61	1-5,28-29,31,34
X	US 3128768 A (GEISTAUTS) 14 April 1964 Column 1 line 55-column 3 line 28	1-5,28-31,34
X	US 5030222 A (CALANDRUCCIO et al.) 9 July 1991 Column 3 line 60-column 4 line 3, column 5 lines 24-34	31-33
<input checked="" type="checkbox"/> Further documents are listed in the continuation of Box C <input checked="" type="checkbox"/> See patent family annex		
* Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier document but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family		
Date of the actual completion of the international search 24 March 1997		Date of mailing of the international search report 02.04.97
Name and mailing address of the ISA/AU: AUSTRALIAN INDUSTRIAL PROPERTY ORGANISATION PO BOX 200 WODEN ACT 2606 AUSTRALIA Facsimile No.: (06) 285 3929		Authorized officer: JOHN HO Telephone No.: (06) 283 2329

INTERNATIONAL SEARCH REPORT

International Application No.

PCT/AU 96/00833

C (Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 4218794 A (SEIDEL et al.) 26 August 1980 Column 2 line 46-column 3 line 6, column 3 lines 48-54	31-33
X	US 5351586 A (HABERMEHL et al.) 4 October 1994 See figures 1-10	31-33
X	GB 2022495 A (MARTIN MAAS) 19 December 1979 See figures 1, 2 and 8	31-33
X	US 3298261 A (LYNN) 17 January 1967 See entire document	31-33
P.X	US 5554154 A (ROSENBERG) 10 September 1996 Column 3 lines 10-31	31
X	US 3835858 A (HAGEN) 17 September 1974 See entire document	31
X	US 2267008 A (ZIMMER) 23 December 1941 Page 1 lines 1-45	31
X	DE 1566114 A (LINK) 22 October 1970 See figures 2-3	31
X	SURGICAL INSTRUMENTS APPLIANCES & HOSPITAL EQUIPMENT, 1930 edition (ALLEN & HANBURY LTD) "Fracture Operation Instruments", pages 590-593 Entire document	31
A	DE 3800482 A (LIST) 20 July 1989 Entire document	

INTERNATIONAL SEARCH REPORT

International Application No.
PCT/AU 96/00833

Box I Observations where certain claims were found unsearchable (Continuation of item 1 of first sheet)

This International Search Report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☐ Claims Nos.:
because they relate to subject matter not required to be searched by this Authority, namely:
2. ☐ Claims Nos.:
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3. ☐ Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a)

Box II Observations where unity of invention is lacking (Continuation of item 2 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

See item at extra sheet.

1. ☒ As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims
2. ☐ As all searchable claims could be searched without effort justifying an additional fee, this Authority did not invite payment of any additional fee.
3. ☐ As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4. ☐ No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

Remark on Protest

- ☐ The additional search fees were accompanied by the applicant's protest.
- ☒ No protest accompanied the payment of additional search fees.

INTERNATIONAL SEARCH REPORT

International Application No.
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Supplemental Box

(To be used when the space in any of Boxes I to VIII is not sufficient)

Continuation of Box No: II

The international application does not comply with the requirements of unity of invention because it does not relate to one invention or to a group of inventions so linked as to form a single general inventive concept. In coming to this conclusion, the International Searching Authority has found that there are three inventions:

- 1 Claims 1-30, 34 are directed to a driver for orthopaedic surgery including a housing, engagement means for releasably engaging the proximal end of a longitudinal driving member, drive means, a longitudinally and coaxially extending shield means connected to an end of the housing and means to permit axial movement of the driven member such that it is always fully shielded and supported by the shield means. The combination of the engagement means, housing, the shield means and the movable means is considered to comprise a first "special technical feature".
- 2 Claim 31 is directed to a plurality of driven members of various type and size having a common sized and shaped proximal ends. This is considered to comprise a second "special technical feature".
- 3 Claim 32 is directed to an adaptor for a driven member having one end a standard sized and shaped head portion for engagement with a drive coupling, and the other end for torque transmitting attachment to a driven member of varying size. This feature is considered to comprise a third "special technical feature".

Since the abovementioned groups of claims do not share any of the technical features identified, a "technical relationship" between the inventions, as defined in PCT Rule 13.2 does not exist. Accordingly, the international application does not relate to one invention or to a single inventive concept.

INTERNATIONAL SEARCH REPORT
Information on patent family members

International Application No.
PCT/AU 96/00833

This Annex lists the known "A" publication level patent family members relating to the patent documents cited in the above-mentioned international search report. The Australian Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent Document Cited in Search Report				Patent Family Member			
US	5030222						
US	4218794	AT	1445/80	AU	55968/80	BR	8001626
		CA	1148338	DE	3009592	DK	941/80
		FR	2451791	GB	2045125	IT	1130307
		JP	55131417	NL	8001305	NZ	193216
		SE	8001523	ZA	8001175	AU	55969/80
		BR	8001329	CA	1141204	DE	3008394
		DK	942/80	FR	2450653	GB	2045125
		JP	55131412	NL	8001307	NZ	193058
		SE	8001522	US	4218795	ZA	8001141
US	5351586	AU	65618/94	AU	59417/96	EP	693018
		WO	9423904	US	5531143		
GB	2022495	BE	876515	CA	1103487	DE	2921083
		DK	2132/79	FR	2432365	IN	152266
		IT	1164003	JP	55005286	MX	147512
		NL	7904012	NO	791609	SE	7904531
		US	4253356				
US	3298261						
US	5554154						
US	3835858	CA	993740	JP	49068378		
DE	1566114						
DE	3800482						
END OF ANNEX							

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